

A method for efficiently calculating head-related transfer functions (HRTFs) directly from head scan point clouds

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Outline

- Introduction
- Motivation
- Method Formulation
- Application
- Validation
- Conclusions
- Future Work

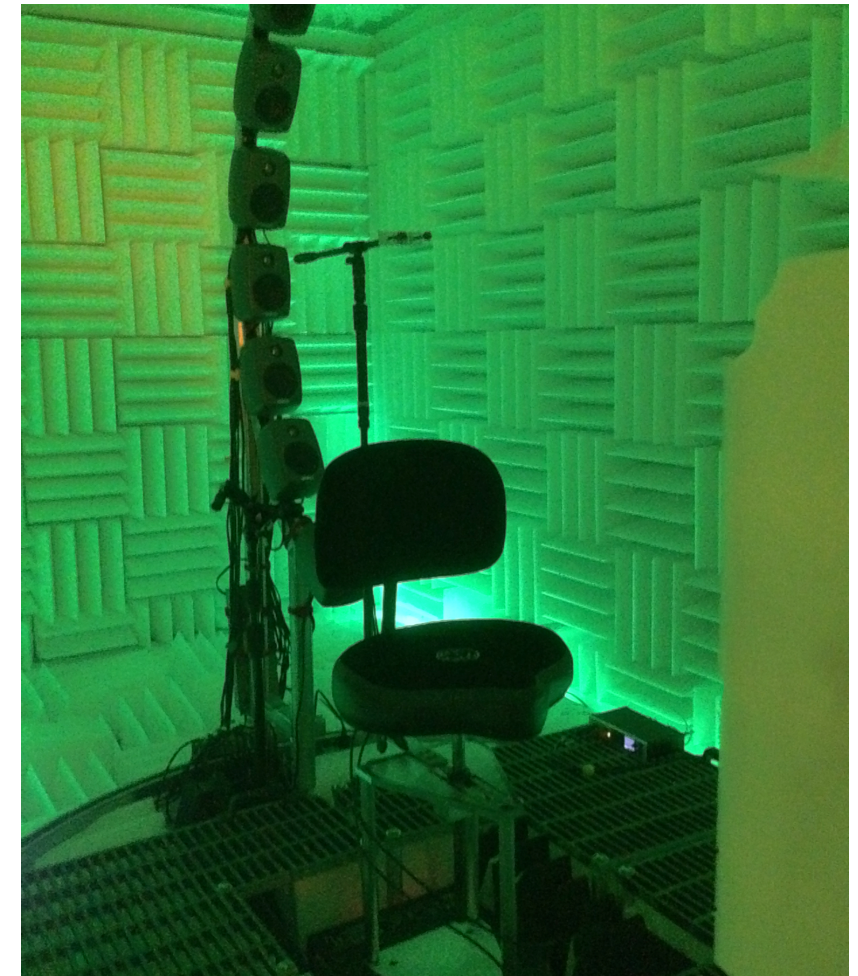
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Introduction

HRTFs from acoustical measurements

- Currently most accurate
- Benchmarks for comparing computed HRTFs
- Requires anechoic chamber
- Cumbersome to set up
- Can be tiresome for subject
- Not ideal for commercial implementation



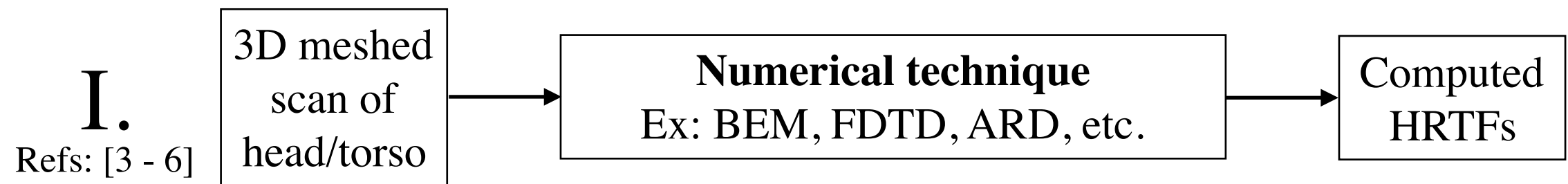
HRTF measurement setup at 3D3A lab

Outline

- Introduction - Acoustically-measured HRTFs are accurate but not ideal for commercial use.
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Motivation

HRTFs from morphological data: Existing methods

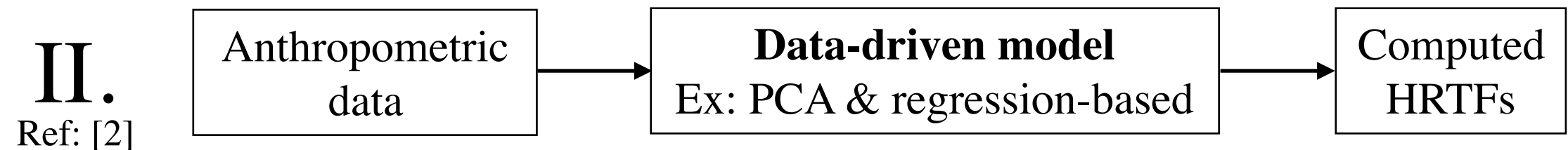


- Computationally expensive.
- Inaccurate without an accurate 3D mesh.

All reference numbers correspond to those in the associated convention paper.

Motivation

HRTFs from morphological data: Existing methods

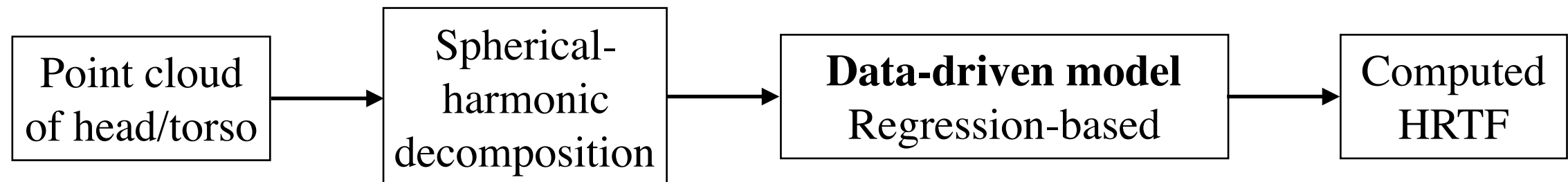


Requires explicit identification and measurement of anthropometric features.

All reference numbers correspond to those in the associated convention paper.

Motivation

HRTFs from morphological data: Proposed method



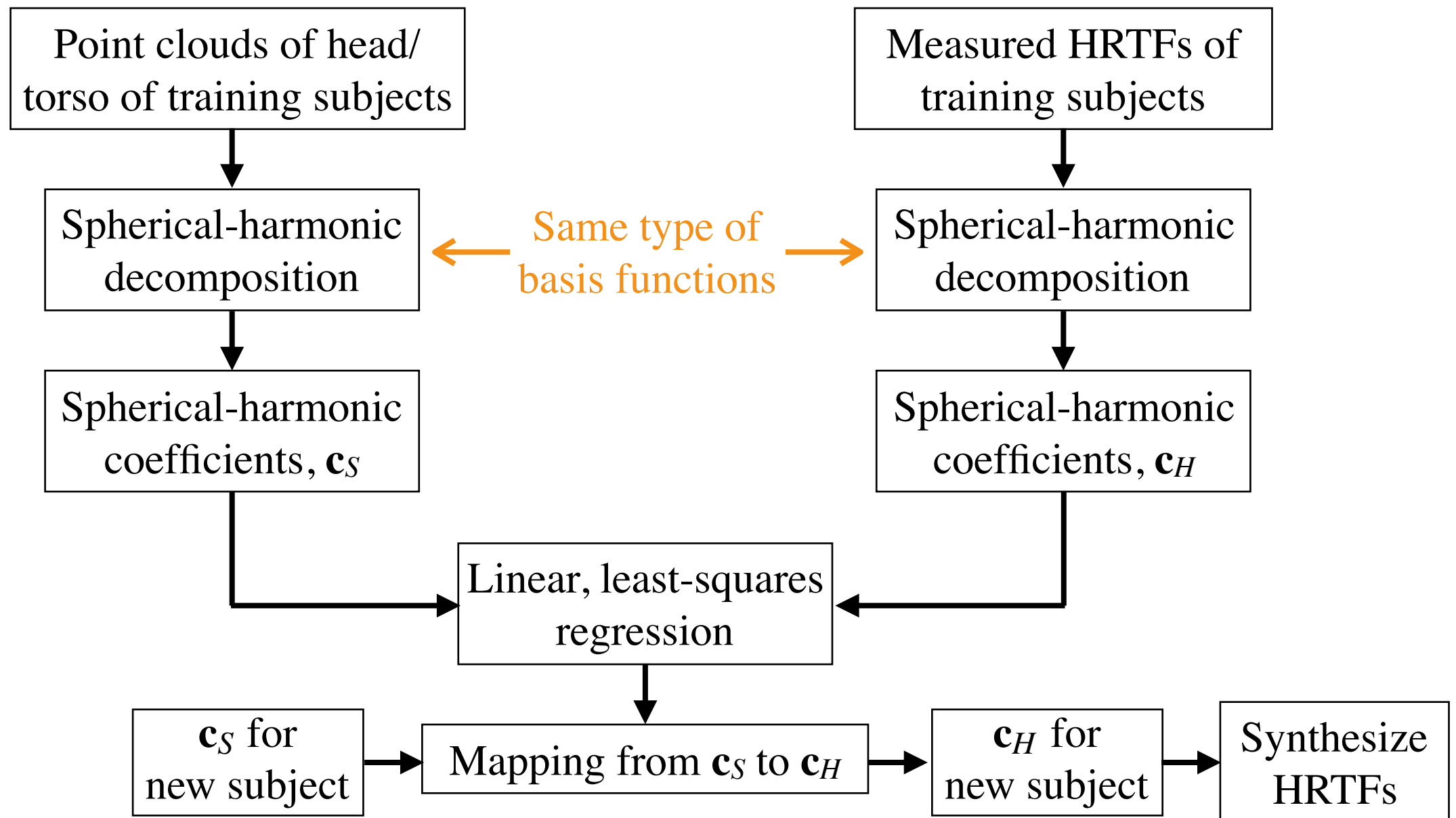
- Requires only point cloud data.
- Computationally inexpensive.
- Does not require explicit identification and measurement of anthropometric features.

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- **Introduction** - Acoustically-measured HRTFs are accurate but not ideal for commercial use.
- **Motivation** - Meshed scans and anthropometric features for computing HRTFs using existing methods are difficult to obtain with required accuracy.
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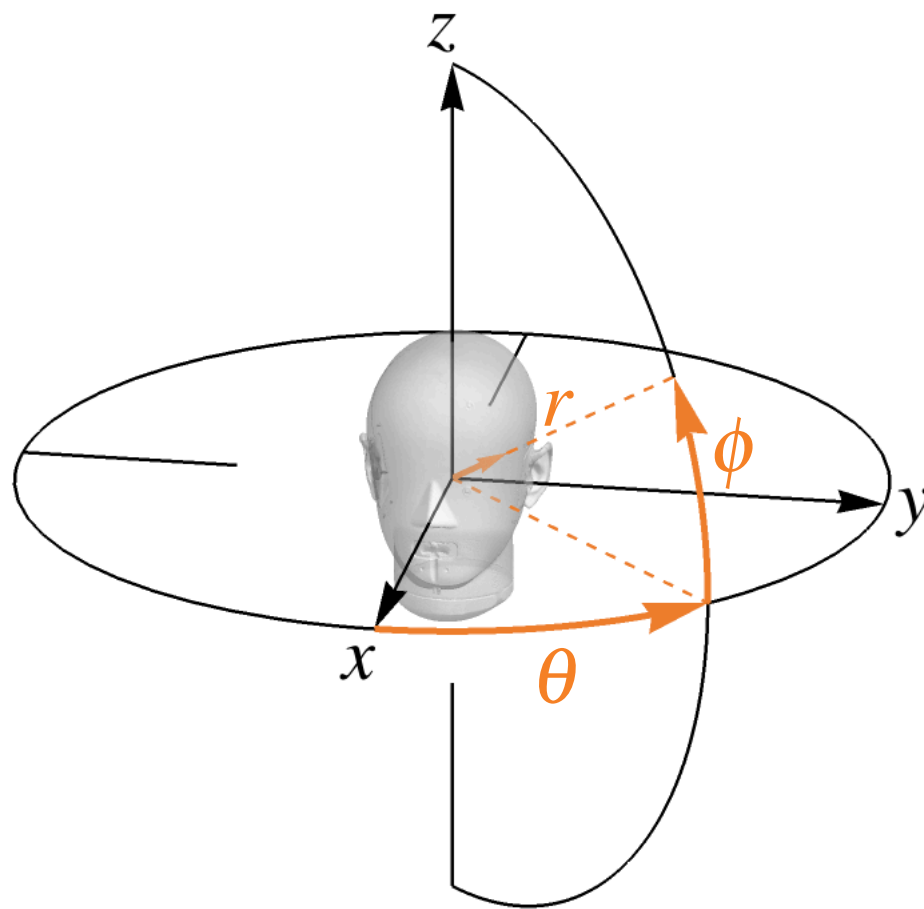
Method Formulation

Basic idea



Method Formulation

Spherical harmonic representation of point cloud data



Represent $r(\theta, \phi)$ using spherical harmonics

Assumption: Scan is already aligned as shown above.

Method Formulation

Spherical harmonic representation of HRTF data

Choose HRTF feature
and represent as spatial
function, $H(\theta, \phi)$



Represent $H(\theta, \phi)$ using
spherical harmonics

Example features:

- (1) ITDs
- (2) HRTF frequency responses
- (3) HRTF magnitude responses

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Application

Data acquisition

Measured HRTF and head scan database	RIEC* [12]
Number of “training” subjects, U	23
HRTF features	(1) HRTF magnitude spectra in dB (cf. [10]) (2) ITD computed by thresholding (cf. [13])

*<http://www.riec.tohoku.ac.jp/pub/hrtf/index.html>

All reference numbers correspond to those in the associated convention paper.

Application

Data pre-processing

- Make measured HRIRs minimum-phase and truncate to 5.8 ms [10].
- Align head scan such that y -axis = interaural axis and x -axis lies in both horizontal and median planes.

All reference numbers correspond to those in the associated convention paper.

Application

Spherical harmonic representation of point cloud data

Maximum possible degree = 3

Mapping to	Degree used
HRTF magnitudes	2
ITDs	1

“Degree” corresponds to degree of spherical harmonic expansion of point cloud data

Application

Spherical harmonic representation of HRTF feature data

Maximum possible degree = 14

HRTF feature	Degree used
HRTF magnitudes in dB	6 (cf. [10])
ITDs	3

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- **Application** - Derive mappings from spherical harmonic representations of point clouds to those of (1) HRTF magnitudes in dB and (2) ITDs.
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Validation

Approach and Metrics

- Number of “test” subjects = 2
- Metric to validate computed HRTF magnitudes: log-weighted average spectral distortion in dB.
- Metric to validate computed ITDs: absolute ITD error.

Validation

Providing Perceptual Context

Approx. perceptibility threshold for rms average spectral distortion

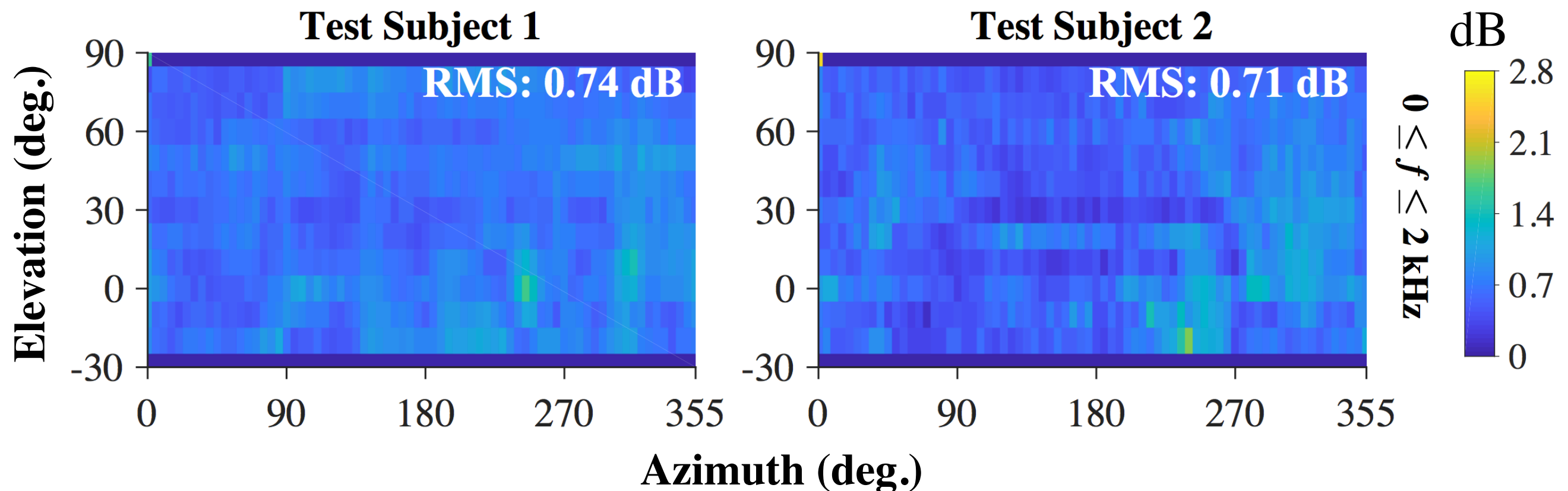
Frequency range (kHz)	Perceptibility threshold (dB)
0 to 2	1
2 to 8	2
8 to 16	3

Approx. perceptibility threshold for absolute ITD error = $30\mu\text{s}$

Validation

Computed HRTF magnitudes

Log-weighted average spectral distortion in dB

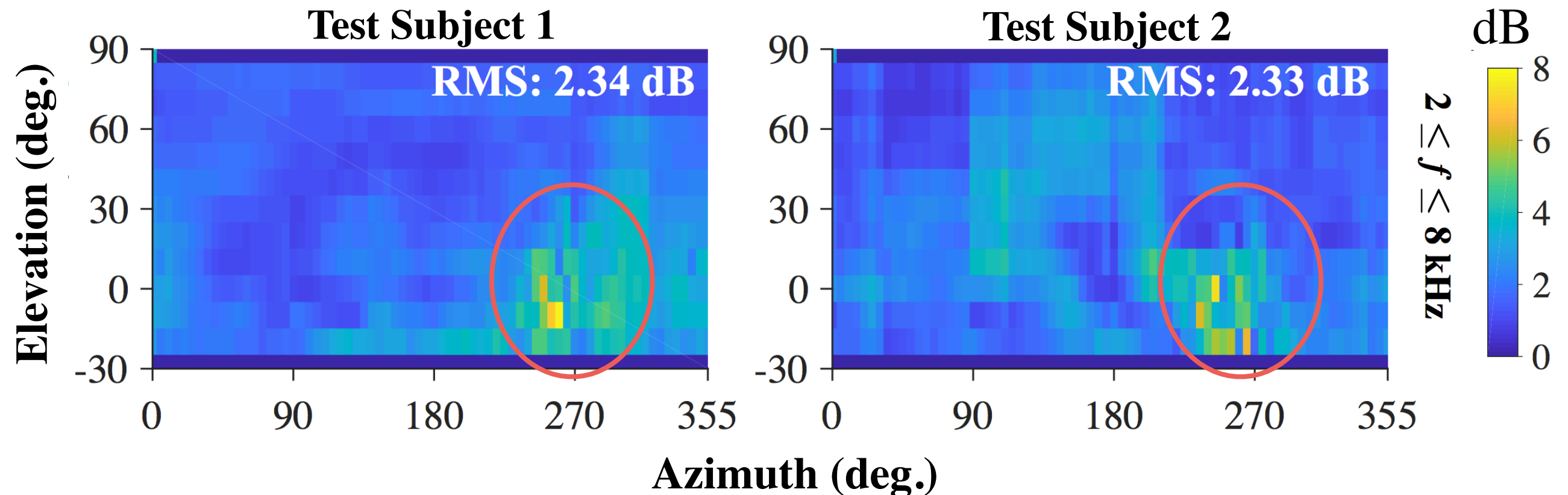


Approx. rms perceptibility threshold = 1 dB

Validation

Computed HRTF magnitudes

Log-weighted average spectral distortion in dB

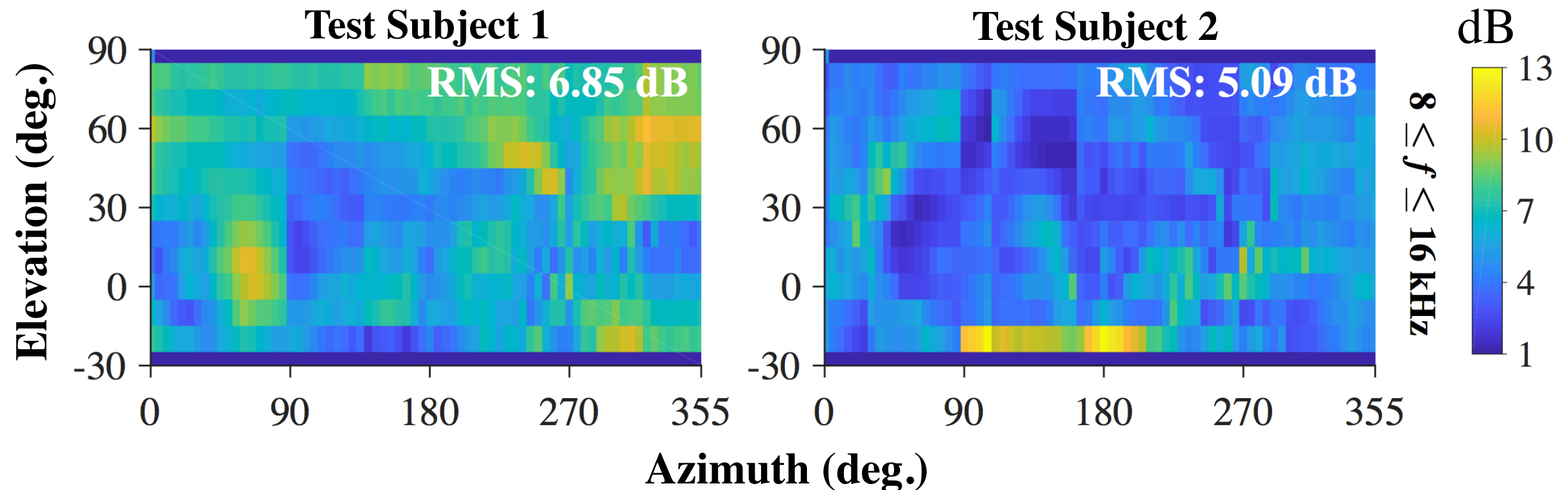


Approx. rms perceptibility threshold = 2 dB

Validation

Computed HRTF magnitudes

Log-weighted average spectral distortion in dB

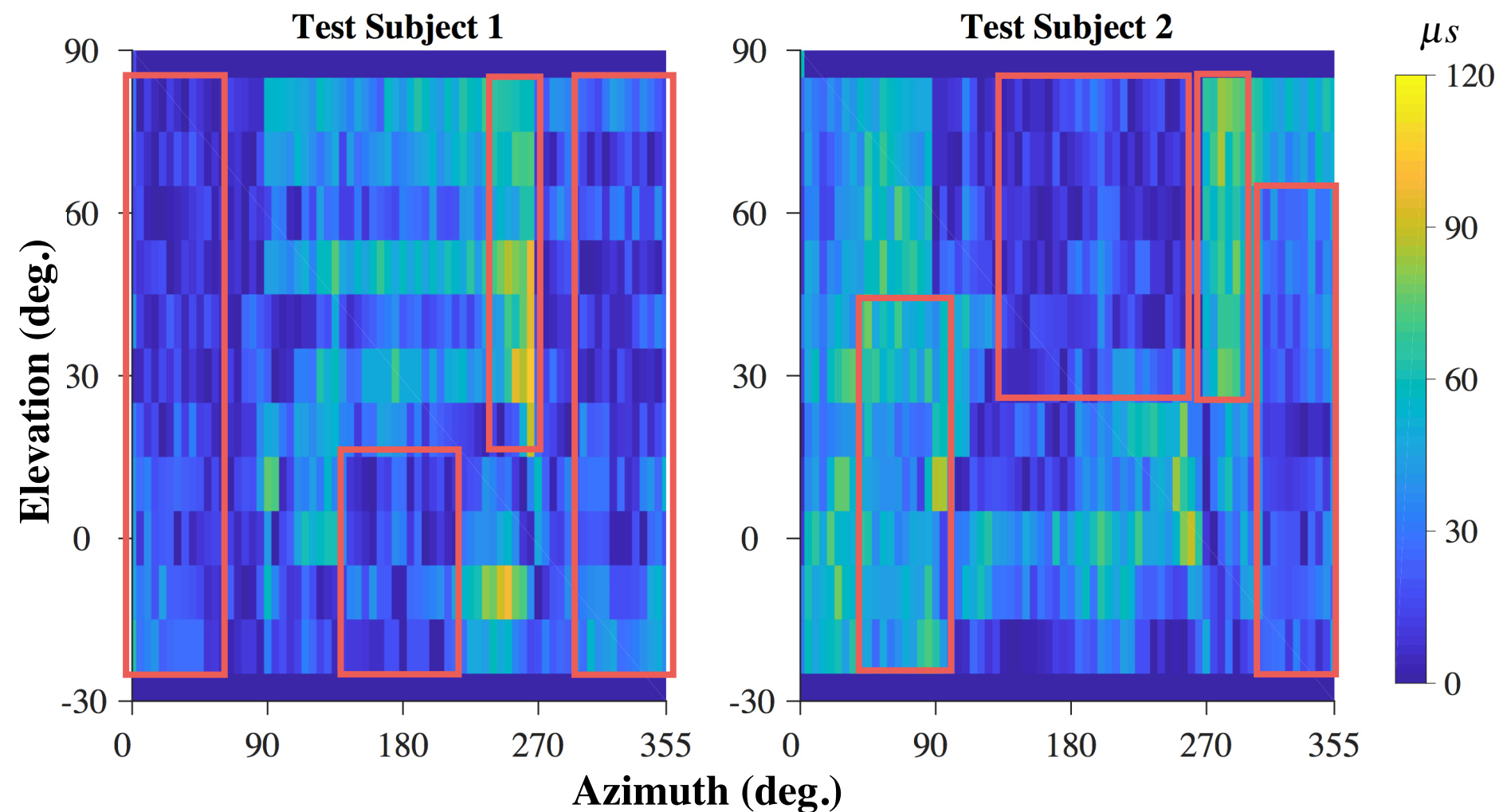


Approx. rms perceptibility threshold = 3 dB

Validation

Computed ITDs

Absolute ITD error in μs

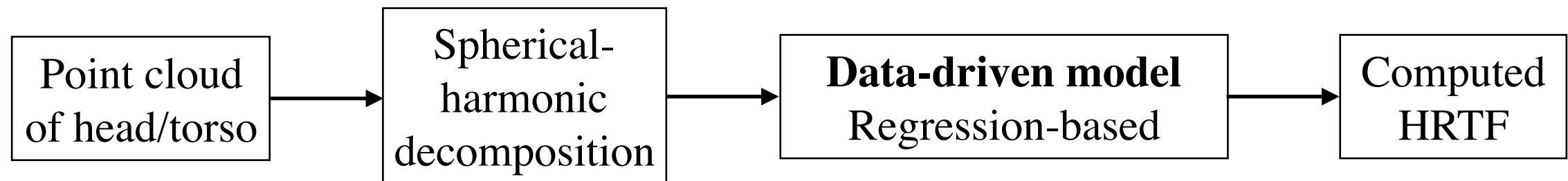


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- **Application** - Derived mappings from spherical harmonic representations of point clouds to those of (1) HRTF magnitudes in dB and (2) ITDs.
- **Validation** - Used two test subjects to objectively show (with perceptual context) that computed HRTFs are accurate up to approx. 6 kHz.
- **Conclusions**
- **Future Work**

Conclusions

- Presented the following method to compute HRTFs from point cloud data of an individual's morphology:



- HRTFs directly from point clouds and no need to identify anthropometric features. This makes it suitable for commercial implementation.
- The current implementation of our method may be used to compute HRTFs that are likely indistinguishable from measured HRTFs for $f < 6$ kHz.
- More data is required to determine how the method performs at higher frequencies. So the 6 kHz limit above may **not** be a limitation of the method.

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- **Application** - Derived mappings from spherical harmonic representations of point clouds to those of (1) HRTF magnitudes in dB and (2) ITDs.
- **Validation** - Used two test subjects to objectively show (with perceptual context) that computed HRTFs are accurate up to approx. 6 kHz.
- **Conclusions** - Our method is suitable to implement commercially, and shows promise for computing HRTFs accurately, but more data is needed.
- **Future Work**

Future Work

- Applying method to larger dataset.
- Trying different types of HRTF features to represent using spherical harmonics.
- Trying different mapping techniques.
- Trying to account for the fact that the head with pinnae is a non-star-shaped object.
- Validation using subjective listening tests.

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